

Problem and scales

Selection of the dendrite tip radius and arm spacing

Scales for tip selection

$$d_0 = \Gamma / (\Delta S \Delta T_0) \quad \text{Capillary length} \quad \sim 10^{-9} \text{m}$$

$$L_{\text{diff}} = 2D / v_{\text{tip}} \quad \text{Diffusion length} \quad \sim 10^{-4} \text{m}$$

$$\text{Peclet number} \quad \text{Pe} = \rho_{\text{tip}} / L_{\text{diff}}$$

$$\text{Selection parameter} \quad \sigma^* = d_0 v_{\text{tip}} / (2D \text{Pe}^2)$$

$$\text{Anisotropy } \varepsilon \text{ defines solution} \quad r_{\text{tip}} = [d_0 L_{\text{diff}} / \sigma^*(\varepsilon)]^{1/2} \sim \mu\text{m}$$

More scales in directional
solidification of alloys:

Primary arm spacing selection

$$L_t = \Delta T_0 / G \quad \text{Solidification length} \quad \sim \text{cm} \quad \lambda \sim (L_t \rho_{\text{tip}})^{1/2} \sim 100 \rho_{\text{tip}}$$

Phase-field equations

Evolution equation for the phase field

$$\frac{\partial \phi_s}{\partial t} = \mu \left[\sigma(\mathbf{n}) \left(\nabla^2 \phi_s + \frac{\pi^2}{2\eta^2} (\phi_s - \phi_l) \right) + \frac{\pi}{\eta} \sqrt{\phi_s \phi_l} \Delta G \right]$$

Evolution equation for the solute concentration

$$\partial_t c + \nabla \cdot (\mathbf{U} \phi_l c_l) = \nabla [D_l \phi_l \nabla c_l] + \nabla \cdot \left[\frac{\eta}{\pi} (c_s - c_l) \partial_t \phi_s \mathbf{n} \right]$$

Driving force

$$\Delta G = \Delta S (T_m - m_l c_l - T)$$

antitrapping
current

Interface energy

η – interface thickness

$$\sigma(\mathbf{n}) = \sigma_0 \left(1 - \frac{3}{2} \varepsilon + \frac{5}{2} \varepsilon (n_x^4 + n_y^4 + n_z^4) \right)$$

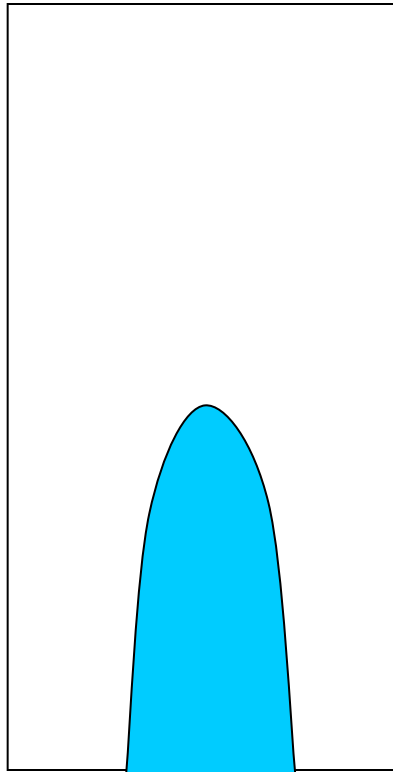
$$c_s = k c_l$$

$$\mathbf{n} = \nabla \phi_s / |\nabla \phi_s|$$

Material and simulation data

Material data of AlCu		Benchmark
Melting point Al	T_m	933.6 K
Liquidus slope	m_l	2.6 K/%
Partition coefficient	k	0.14
Liquid diffusivity	D_l	$3 \times 10^{-9} \text{ m}^2/\text{s}$
Interface energy	σ_0	$0.24 \text{ J}/\text{m}^2$
Interface anisotropy	ε	0.3
Entropy of fusion	ΔS	$10^6 \text{ J}/(\text{m}^3 \text{ K})$
Grid spacing	Δx	$0.4 - 1.5 \mu\text{m}$
Interface thickness	η	$1.6 - 9 \mu\text{m}$
Temperature gradient	$\partial T / \partial z$	$10^4 \text{ K}/\text{m}$
Cooling rate	$\partial T / \partial t$	$0.4 \text{ K}/\text{s}$

Effect of the grid spacing



Domain size: $L_X = L_Y = 100 \mu m$
 $L_z = 270 \mu m$

Grid spacing: 0.4, 0.5, 0.6, 0.8, ... 1.5 μm

Dendrite length: 120 μm

Growth velocity: $V_g = \frac{\partial T / \partial t}{\partial T / \partial z} = 40 \frac{\mu m}{s}$

Diffusion length: $L_{diff} = \frac{2D_l}{V_g} = 150 \mu m$

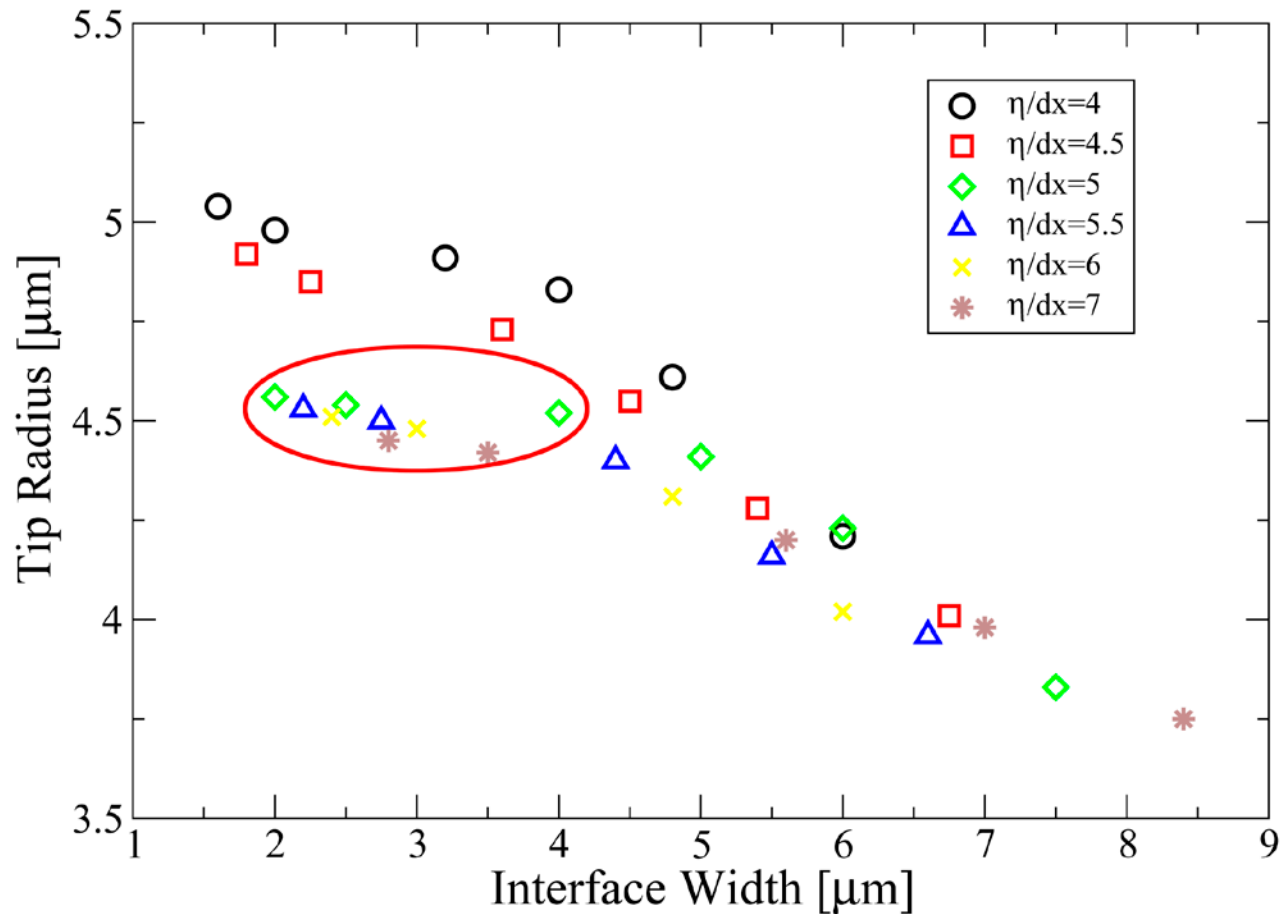
Boundary conditions:

Phase Field : Zero gradient

Concentration Field : Fixed 4% (top), zero gradient (others)

Simulation results: convergence check

Convergence for different grid spacing and interface width



Simulation results: spacing selection

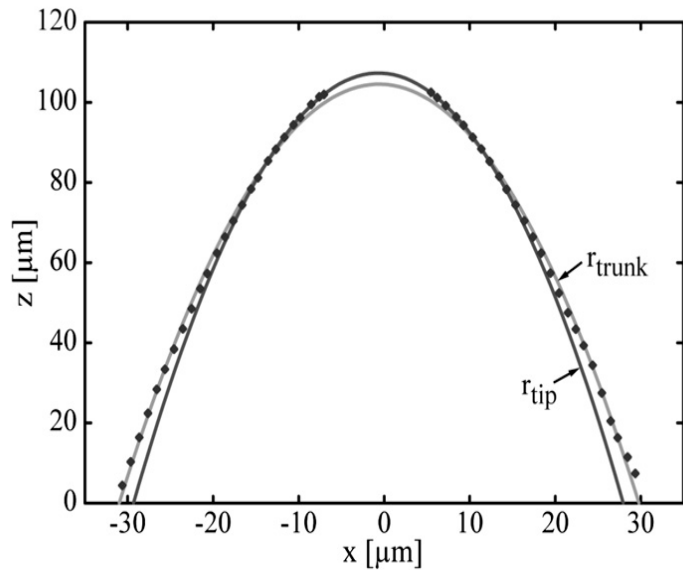
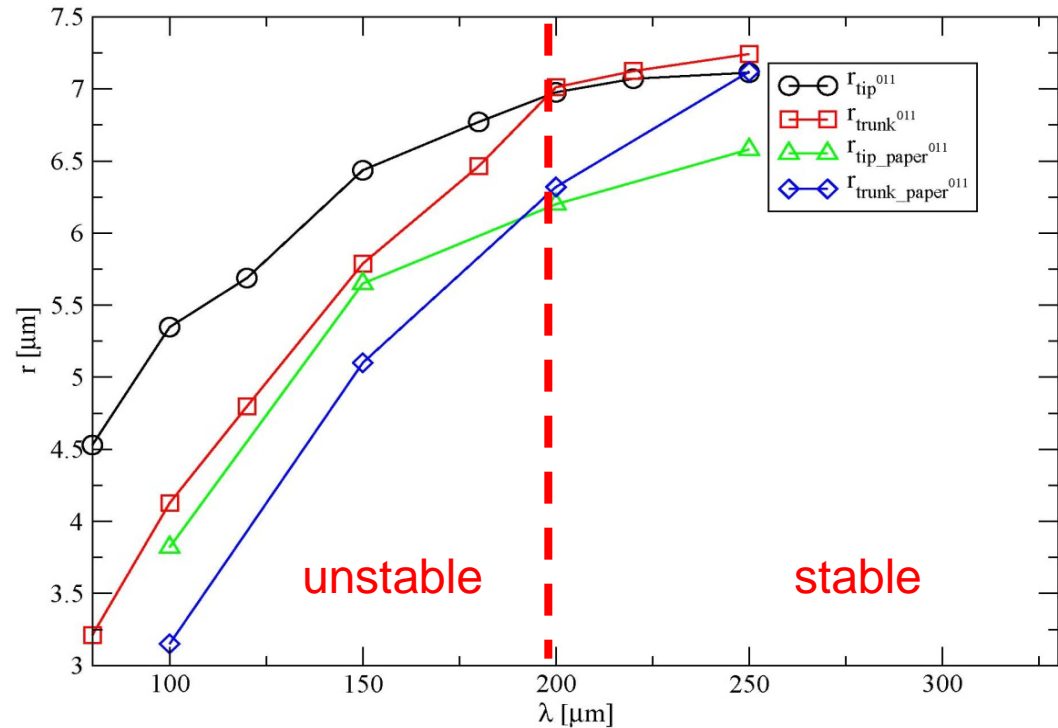


Fig. 6. Plot of the phase-field contour points with the fitted parabola r_{tip} and r_{trunk} . (Note the different scale on the x - and z -axes.).



Green & Blue lines are taken from "I. Steinbach. Acta Mat. 56 (2008) 4965-4971"